

Having thus described the invention, it is now claimed:

1. A system for organizing multi-dimensional pattern data into a reduced-dimension representation comprising:

a neural network comprised of a plurality of layers of nodes, the plurality of layers including:

an input layer comprised of a plurality of input nodes,

a hidden layer, and

an output layer comprised of a plurality of non-linear output nodes, wherein the number of non-linear output nodes is less than the number of input nodes;

receiving means for receiving multi-dimensional pattern data into the input layer of the neural network;

output means for generating an output signal for each of the output nodes of the output layer of the neural network corresponding to received multi-dimensional pattern data; and

training means for completing a training of the neural network, wherein the training means includes means for equalizing and orthogonalizing the output signals of the output nodes by reducing a covariance matrix of the output signals to the form of a diagonal matrix.

2. A system according to claim 1, wherein said training means uses backpropagation to iteratively update weights for the links between nodes of adjacent layers.

3. A system according to claim 2, wherein said weights are generated randomly in the interval (W, -W).

4. A system according to claim 3, wherein averaged variance of all dimensions of the multi-dimensional pattern data is:

$$V_{in} = \frac{1}{SP} \sum_{i=1}^S \sum_{p=1}^P (x_{ip} - \langle x_i \rangle)^2$$

,and the elements of the covariance matrix of the output signals of the output nodes are defined by:

$$V_{out,k_1,k_2} = \frac{1}{P} \sum_{p=1}^P (O_{k_1p} - \langle O_{k_1} \rangle)(O_{k_2p} - \langle O_{k_2} \rangle)$$

,where $p=1,2,\dots,P$;

O_{k_1p} is the output signal of the k_1 th node of the output layer for the p th input data pattern vector;

O_{k_2p} is the output signal of the k_2 th node of the output layer for the p th input data pattern vector;

$\langle O_{k_1} \rangle$ is the average of $O_{k,p}$ evaluated over the set of input data pattern vectors

$\langle O_{k_2} \rangle$ is the average of $O_{k,p}$ evaluated over the set of input data pattern vectors

$k_1 = 1$ to K ;

$k_2 = 1$ to K ;

K is the number of dimensions in the reduced-dimension representation; and

$\langle \rangle$ denotes the mean evaluated over the set of input data pattern vectors for each indicated component.

5. A system according to claim 4, wherein weights Δw_{kj} between the hidden layer and the output layer are iteratively updated according to the expression:

$$\begin{aligned} \Delta w_{kj} &= -\eta \frac{\partial E}{\partial w_{kj}} = \frac{1}{P} \sum_{p=1}^P \eta \delta_{kp} O_{jp} \\ &= -\eta \left(\frac{\partial E_{kk}}{\partial w_{kj}} + \sum_{k_2=k+1}^K \frac{\partial E_{kk_2}}{\partial w_{kj}} + \sum_{k_1=1}^{k-1} \frac{\partial E_{k_1k}}{\partial w_{kj}} \right) \\ &= \Delta w_{kj,1} + \Delta w_{kj,2} + \Delta w_{kj,3} \end{aligned}$$

, where η is a constant of suitable value chosen to provide efficient convergence but to avoid oscillation;

O_{jp} is the output signal from the j th node in the layer preceeding the output layer due to the p th input data pattern vector;

E is the error given by:

$$E = \sum_{k_1=1}^K \sum_{k_2=k_1}^K E_{k_1 k_2}$$

and,

$$E_{k_1 k_2} = \left(\frac{V_{out, kk} - r_{kk} V_{in}}{r_{kk} V_{in}} \right)^2$$

,where $k_1 = k_2 = k$; $k = 1, \dots, K$; and r_{kk} is a positive constant which has an effect of increasing the speed of training,

$$E_{k_1 k_2} = \left(\frac{V_{out, k_1 k_2}}{r_{k_1 k_2} V_{in}} \right)^2$$

,where $k_2 > k_1$; $k_1 = 1, \dots, K-1$; $k_2 = k_1 + 1, \dots, K$; and $r_{k_1 k_2}$ is a positive constant which has an effect of increasing the speed of training; and

$\delta_{kp} = \delta_{kp,1} + \delta_{kp,2} + \delta_{kp,3}$, where δ_{kp} is a value proportional to the contribution to the error E by the outputs of the k th node of the output layer, for the p th input data pattern vector, and $\delta_{kp,1}$, $\delta_{kp,2}$, and $\delta_{kp,3}$ are components of δ_{kp} .

6. A system according to claim 5, wherein:

$$\Delta w_{kj,1} = -\eta \frac{\partial E_{kk}}{\partial w_{kj}} = \frac{1}{P} \sum_{p=1}^P \eta \delta_{kp,1} O_{jp}$$

$$\Delta w_{kj,2} = -\eta \sum_{k_2=k+1}^K \frac{\partial E_{kk_2}}{\partial w_{kj}} = \frac{1}{P} \sum_{p=1}^P \eta \delta_{kp,2} O_{jp}$$

$$\Delta w_{kj,3} = -\eta \sum_{k_1=1}^{k-1} \frac{\partial E_{k_1k}}{\partial w_{kj}} = \frac{1}{P} \sum_{p=1}^P \eta \delta_{kp,3} O_{jp}$$

where $\Delta w_{kj,1}$ is the contribution from the diagonal terms of the covariance matrix of the outputs,

$\Delta w_{kj,2}$ is the contribution from the off-diagonal terms in k th row,

$\Delta w_{kj,3}$ is the contribution from the off-diagonal terms in k th column, and

O_{jp} is the output signal from the j th node in the layer preceeding the output layer for the p th input data pattern vector.

7. A system according to claim 6, wherein:

$$\delta_{kp,1} = 4 (V_{out,kk} - r_{kk} V_{in})(\langle O_k \rangle - O_{kp}) O_{kp} (1 - O_{kp})$$

$$\delta_{kp,1} = 2 \left(\sum_{k_2=k+1}^K V_{out,kk_2} (\langle O_k \rangle - O_{kp}) \right) O_{kp} (1 - O_{kp})$$

$$\delta_{kp,3} = 2 \left(\sum_{k_1=1}^{k-1} V_{out,k_1k} (\langle O_k \rangle - O_{kp}) \right) O_{kp} (1 - O_{kp})$$

, where

O_{kp} is the output signal from the kth node in the output layer for the pth input data pattern vector, and

$\langle O_{kp} \rangle$ is the average of O_{kp} evaluated over the set of input data pattern vectors.

8. A system according to claim 5, wherein backpropagation of error to the weights Δw_{ji} between the jth node in a layer of nodes and the ith node in its' preceeding layer:

$$\Delta w_{ji} = \eta \frac{\partial E}{\partial w_{ji}} = \frac{1}{P} \sum_{p=1}^P \eta \delta_{jp} x_{ip}$$

where, δ_{jp} is given by:

$$\delta_{jp} = \left(\sum_{k=1}^K \delta_{kp} w_{kj} \right) O_{jp} (1 - O_{jp})$$

9. A method for effecting the organization of multi-dimensional pattern data into a reduced dimensional representation using a neural network having an input layer comprised of a plurality of input nodes, a hidden layer, and an output layer comprised of a plurality of non-linear output nodes, wherein the number of non-linear output nodes is less than the number of input nodes, said method comprising:

receiving multi-dimensional pattern data into the input layer of the neural network;

generating an output signal for each of the output nodes of the neural network corresponding to received multi-dimensional pattern data; and

training the neural network by equalizing and orthogonalizing the output signals of the output nodes by reducing a covariance matrix of the output signals to the form of a diagonal matrix.

10. A method according to claim 9, wherein said step of training includes backpropagation to iteratively update weights for links between nodes of adjacent layers.

11. A method according to claim 10, wherein said weights are generated randomly in the interval (W, -W).

12. A method according to claim 11, wherein averaged variance of all dimensions of the multi-dimensional pattern data is:

$$V_{in} = \frac{1}{SP} \sum_{i=1}^S \sum_{p=1}^P (x_{ip} - \langle x_i \rangle)^2$$

,and the elements of the covariance matrix of the output signals of the output nodes is:

$$V_{out,k_1k_2} = \frac{1}{P} \sum_{p=1}^P (O_{k_1p} - \langle O_{k_1} \rangle)(O_{k_2p} - \langle O_{k_2} \rangle)$$

,where $p=1,2,\dots,P$;

O_{k_1p} is the output signal of the k_1 th node of the output layer for the p th input data pattern vector;

O_{k_2p} is the output signal of the k_2 th node of the output layer for the p th input data pattern vector;

$\langle O_{k_1 p} \rangle$ is the average of $O_{k_1 p}$ evaluated over the set of input data pattern vectors

$\langle O_{k_2 p} \rangle$ is the average of $O_{k_2 p}$ evaluated over the set of input data pattern vectors

$k_1 = 1$ to K ;

$k_2 = 1$ to K ;

K is the number of dimensions in the reduced-dimension representation; and

$\langle \rangle$ denotes the mean evaluated over the set of input data pattern vectors for each indicated component.

13. A method according to claim 12, wherein weights Δw_{kj} between the hidden layer and the output layer are iteratively updated according to the expression:

$$\begin{aligned} \Delta w_{kj} &= -\eta \frac{\partial E}{\partial w_{kj}} = \frac{1}{P} \sum_{p=1}^P \eta \delta_{kp} O_{jp} \\ &= -\eta \left(\frac{\partial E_{kk}}{\partial w_{kj}} + \sum_{k_2=k+1}^K \frac{\partial E_{kk_2}}{\partial w_{kj}} + \sum_{k_1=1}^{k-1} \frac{\partial E_{k_1 k}}{\partial w_{kj}} \right) \\ &= \Delta w_{kj,1} + \Delta w_{kj,2} + \Delta w_{kj,3} \end{aligned}$$

, where η is a constant of suitable value chosen to provide efficient convergence but to avoid oscillation;

O_{jp} is the output signal from the j th node in the layer preceeding the output layer, due to the p th input data pattern vector;

E is the error given by:

$$E = \sum_{k_1=1}^K \sum_{k_2=k_1}^K E_{k_1 k_2}$$

and,

$$E_{k_1 k_2} = \left(\frac{V_{out, kk} - r_{kk} V_{in}}{r_{kk} V_{in}} \right)^2$$

,where $k_1 = k_2 = k$; $k = 1, \dots, K$; and r_{kk} is a positive constant which has an effect of increasing the speed of training,

$$E_{k_1 k_2} = \left(\frac{V_{out, k_1 k_2}}{r_{k_1 k_2}} V_{in} \right)^2$$

,where $k_2 > k_1$; $k_1 = 1, \dots, K-1$; $k_2 = k_1 + 1, \dots, K$; and $r_{k_1 k_2}$ is a positive constant which has an

effect of increasing the speed of training; and

$\delta_{kp} = \delta_{kp,1} + \delta_{kp,2} + \delta_{kp,3}$, where δ_{kp} is a value proportional to the contribution to the error E by the outputs of the k th node of the output layer, for the p th input data pattern vector, and $\delta_{kp,1}$, $\delta_{kp,2}$, and $\delta_{kp,3}$ are components of δ_{kp}

14. A method according to claim 13, wherein:

$$\Delta w_{kj,1} = -\eta \frac{\partial E_{kk}}{\partial w_{kj}} = \frac{1}{P} \sum_{p=1}^P \eta \delta_{kp,1} O_{jp}$$

$$\Delta w_{kj,2} = -\eta \sum_{k_2=k+1}^K \frac{\partial E_{kk_2}}{\partial w_{kj}} = \frac{1}{P} \sum_{p=1}^P \eta \delta_{kp,2} O_{jp}$$

$$\Delta w_{kj,3} = -\eta \sum_{k_1=1}^{k-1} \frac{\partial E_{k_1k}}{\partial w_{kj}} = \frac{1}{P} \sum_{p=1}^P \eta \delta_{kp,3} O_{jp}$$

where $\Delta w_{kj,1}$ is the contribution from the diagonal term,

$\Delta w_{kj,2}$ is the contribution from the off-diagonal terms in k th row, and

$\Delta w_{kj,3}$ is the contribution from the off-diagonal terms in k th column.

15. A method according to claim 14, wherein $\delta_{kp,1}$, $\delta_{kp,2}$ and $\delta_{kp,3}$ are given

by:

$$\delta_{kp,1} = 4(V_{out,kk} - r_{kk} V_{in})(\langle O_k \rangle - O_{kp}) O_{kp} (1 - O_{kp})$$

$$\delta_{kp,1} = 2 \left(\sum_{k_2=k+1}^K V_{out,kk_2} (\langle O_k \rangle - O_{kp}) \right) O_{kp} (1 - O_{kp})$$

$$\delta_{kp,3} = 2 \left(\sum_{k_1=1}^{k-1} V_{out,k_1k} (\langle O_k \rangle - O_{kp}) \right) O_{kp} (1 - O_{kp})$$

, where

O_{kp} is the output signal from the kth node in the layer preceeding the output layer for the pth input data pattern vector, and

$\langle O_{kp} \rangle$ is the average of O_{kp} evaluated over the set of input data pattern vectors.

16. A method according to claim 13, wherein backpropogation of error to the weights Δw_{ji} between the jth node in a layer of nodes and the ith node in its' preceeding layer are:

$$\Delta w_{ji} = \eta \frac{\partial E}{\partial w_{ji}} = \frac{1}{P} \sum_{p=1}^P \eta \delta_{jp} x_{ip}$$

where, δ_{jp} is given by:

$$\delta_{jp} = \left(\sum_{k=1}^K \delta_{kp} w_{kj} \right) O_{jp} (1 - O_{jp})$$

17. A system for organizing multi-dimensional pattern data into a reduced dimensional representation comprising:

a neural network comprised of a plurality of layers of nodes, the plurality of layers including:

an input layer comprised of a plurality of input nodes, and

an output layer comprised of a plurality of non-linear output nodes, wherein the number of non-linear output nodes is less than the number of input nodes;

receiving means for receiving multi-dimensional pattern data into the input layer of the neural network;

output means for generating an output signal at the output layer of the neural network corresponding to received multi-dimensional pattern data; and

training means for completing a training of the neural network, wherein the training means conserves a measure of the total variance of the output nodes, wherein the total variance of the output nodes is defined as:

$$V=(1/P)\sum_{p=1}^{p=P}\sum_{i=1}^{i=S}(x_{ip}-\langle x_i \rangle)^2$$

,where $\{x_p\}$ is a set of data pattern vectors;

$p=1,2,\dots,P$;

P is defined as a positive integer;

$\langle x_i \rangle$ denotes the mean value of x_{ip} evaluated over the set of data pattern vectors;

S is the number of dimensions;

x_{ip} is the i th component of x_p , the p th member of a set of data pattern vectors.

18. A system according to claim 17, wherein said training means completes the training of the neural network via backpropagation for progressively changing weights for the output nodes.

19. A system according to claim 18, wherein said training means further includes,

means for training the neural network by backpropagation by progressively changing weights w_{kj} at the output layer of the neural network in accordance with,

$$\Delta w_{kj} = (1/P) \sum_{p=1}^{p=P} \Delta w_{p,kj} = (1/P) \sum_{p=1}^{p=P} \eta \delta_{pk} O_{pj}$$

, where O_{pj} is the output signal from the j th node in the layer preceeding the output layer due to the p th data pattern,

η is a constant of suitable value chosen to provide efficient convergence but to avoid oscillation, and

δ_{pk} is a value proportional to the contribution to the error E by the outputs of the k th node of the output layer for the p th input data pattern.

20. A system according to claim 19, wherein:

$$\delta_{pk} = [V - (1/P) \sum_q \sum_n (O_{qn} - \langle O_n \rangle^2)] (O_{pk} - \langle O_k \rangle) O_{pk} (1 - O_{pk})$$

21. A system according to claim 19, wherein said neural network further comprises at least one hidden layer comprised of hidden nodes, wherein adaptive weights w_{ji} for each hidden node is progressively improved in accordance with,

$$\Delta w_{ji} = -\eta \frac{\partial E}{\partial w_{ji}} = \frac{1}{P} \sum_{p=1}^{p=P} \eta \delta_{pj} O_{pi}$$

, where O_{pi} is the output signal for the i th node of the layer preceeding the j th layer of the p th input data pattern.

22. A system according to claim 21, wherein:

$$\delta_{pj} = \left(\sum_{k=1}^K \delta_{pk} w_{kj} \right) O_{pj} (1 - O_{pj})$$

23. A method for effecting the organization of multi-dimensional pattern data into a reduced dimensional representation using a neural network having an input layer comprised of a plurality of input nodes, and an output layer comprised of a plurality of non-linear output nodes, wherein the number of non-linear output nodes are less than the number of input nodes, said method comprising:

receiving a set $\{x_p\}$ of data pattern vectors into the input layer of the neural network, wherein $p=1,2,\dots,P$ and wherein P is defined as a positive integer, and wherein the set of data pattern vectors has a total variance defined as,

$$V=(1/P)\sum_{p=1}^{p=P}\sum_{i=1}^{i=S}(x_{ip}-\langle x_i \rangle)^2$$

,where $\{x_p\}$ is a set of data pattern vectors;

$p=1,2,\dots,P$;

P is defined as a positive integer;

$\langle x_i \rangle$ denotes the mean value of x_{ip} evaluated over the set of data pattern vectors;

S is the number of dimensions;

x_{ip} is the i th component of x_p , the p th member of a set of data pattern vectors;

training the neural network by backpropagation; and

displaying a multi-dimensional output signal from the output layer of the neural network.

24. A method according to claim 23, wherein said step of training the neural network by backpropagation includes progressively changing weights w_{kj} at the output layer of the neural network in accordance with,

$$\Delta w_{kj} = (1/P) \sum_{p=1}^{p=P} \Delta w_{p,kj} = (1/P) \sum_{p=1}^{p=P} \eta \delta_{pk} O_{pj}$$

, where O_{pj} is the output signal from the j th node in the layer preceeding the output layer due to the p th data pattern, and

η is a constant of suitable value chosen to provide efficient convergence but to avoid oscillation.

δ_{pk} is a value proportional to the contribution to the error E by the outputs of the k th node of the output layer for the p th input data pattern.

25. A system according to claim 24, wherein:

$$\delta_{pk} = [V - (1/P) \sum_q \sum_n (O_{qn} - \langle O_n \rangle^2)] (O_{pk} - \langle O_k \rangle) O_{pk} (1 - O_{pk})$$

26. A method according to claim 23, wherein said neural network further comprises at least one hidden layer comprised of hidden nodes, wherein adaptive weights w for each hidden node of the neural network is progressively improved in accordance with,

$$\Delta w_{ji} = -\eta \frac{\partial E}{\partial w_{ji}} = \frac{1}{P} \sum_{p=1}^{p=P} \eta \delta_{pj} O_{pi}$$

, where O_{pi} is the output signal for the i th node of the layer preceeding the j th layer of the p th input data pattern.

27. A method according to claim 26, wherein

$$\delta_{pj} = \left(\sum_{k=1}^K \delta_{pk} w_{kj} \right) O_{pj} (1 - O_{pj})$$

28. A method according to claim 23, wherein said multi-dimensional output signal is a two-dimensional output signal.

29. A method according to claim 23, wherein said two-dimensional output signal includes data points plotting in relation to 2-dimensional axes.